

1.	Title of the course	Modeling and Control of Electric Machines
2.	Course number	EE405L
3.	Structure of credits	3-0-0-3
4.	Offered to	UG
5.	New course/modification to	Modification To EE4023/12
6.	To be offered by	Department of Electrical Engineering
7.	To take effect from	July 2022
8.	Prerequisite	CoT for UG
9.	Course Objective(s): To introduce the dynamic behavior of AC machines through modeling, analysis and control of a three phase induction motor drive.	
	Course Content: Principle of unified machine theory, generalized torque equation; Performance evaluation of DC machine and speed control; Three phase induction motor: transformation methods, (stationary, rotor and synchronous frames) and corresponding equivalent circuits; Reduced order dynamic modeling, scalar and vector control (rotor field oriented control, stator field oriented and air gap field oriented control) of induction machine; Simulation and controller design for the different control algorithms.	
10.	Course Content: Principle of unified machine evaluation of DC machine and speed conta methods, (stationary, rotor and synchronous Reduced order dynamic modeling, scalar and v oriented and air gap field oriented control) of inc the different control algorithms.	e theory, generalized torque equation; Performance rol; Three phase induction motor: transformation is frames) and corresponding equivalent circuits; vector control (rotor field oriented control, stator field duction machine; Simulation and controller design for
10.	 Course Content: Principle of unified machine evaluation of DC machine and speed continethods, (stationary, rotor and synchronous Reduced order dynamic modeling, scalar and voriented and air gap field oriented control) of indite different control algorithms. Textbook(s): Boldea I and Nasar A, <i>Electric Drives</i>, 1st Ed Chapman S J, <i>Electric Machinery Fundamer</i> 	e theory, generalized torque equation; Performance rol; Three phase induction motor: transformation is frames) and corresponding equivalent circuits; vector control (rotor field oriented control, stator field duction machine; Simulation and controller design for dition, CRC Press (1998).